DH-ROBOTICS





PGLS Series Industrial Flat Electric Grippers

PGLS-700





Product Features

> Thin | High energy density

The PGLS-700 heavy-duty electric gripper is compact in design and only 50mm thick. It has high gripping force, fast gripping cycle and built-in power-off hold function. This gripper challenges the limits of large load, compactness and thinness.

> High force control accuracy

The force repeatability is $\pm 70N(\pm 10\%)$, far better than ordinary products in the market by $\pm 10\% \sim \pm 20\%$ of force control accuracy.

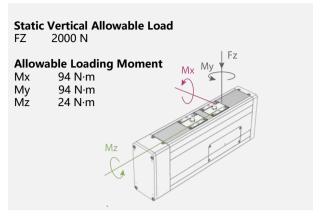
Quick response | Intelligent planning speed

Opening/closing time up to 1.0s/1.1s(100 stroke), with speed control optimization and mechanical self-locking mechanism function, it can meet fast and stable gripping needs of the production line.



■ PGLS-700-100

> Product Parameter	
Gripping force(per jaw)	240~700 N
Total stroke	100 mm
Recommend payload*①	8 kg
Opening/closing time	1.0 s/1.1 s
Repeat accuracy(position)	± 0.02 mm
Operating noise	< 75 dB
Weight	2.7 kg
Diving method	Precision reduction box + ball screw + built-in guide rail
Size	262 mm x 98 mm x 50 mm



*① It depends on factors such as the shape of the grasped object, the contact surface material and friction, and the acceleration of the movement; the center of gravity offset of the grasped object will also affect the load. If you have any questions, please consult us.

> Working Environment

Communication

Standard: IO-Link Modbus RTU (RS485), Optional: TCP/IP、USB2.0、CAN2.0A、PROFINET、EtherCAT *② interface

24 V DC ± 10% Rated voltage

Rated current 4.5 A

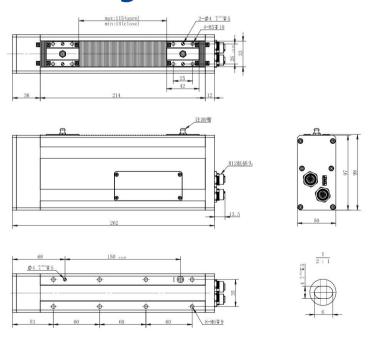
Peak current 13.5 A

IP class **IP 40**

Recommend 0~40°C, under 85% RH environment

Certification CE, FCC, RoHS



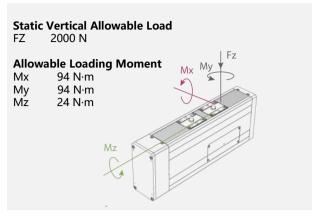


^{*}② Using the optional communication protocol, an external communication conversion box is required. Please consult the sales staff for details.



■ PGLS-700-200

> Product Parameter	
Gripping force(per jaw)	240~700 N
Total stroke	200 mm
Recommend payload*①	8 kg
Opening/closing time	2.0 s/2.1 s
Repeat accuracy(position)	± 0.02 mm
Operating noise	< 75 dB
Weight	3.7 kg
Diving method	Precision reduction box + ball screw + built-in guide rail
Size	382 mm x 98 mm x 50 mm



*① It depends on factors such as the shape of the grasped object, the contact surface material and friction, and the acceleration of the movement; the center of gravity offset of the grasped object will also affect the load. If you have any questions, please consult us.

> Working Environment

Communication interface

Standard: IO-Link Modbus RTU (RS485), Optional: TCP/IP、USB2.0、CAN2.0A、PROFINET、EtherCAT *②

24 V DC ± 10% Rated voltage

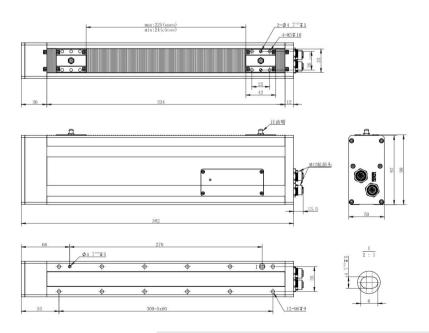
Rated current 4.5 A

Peak current 13.5 A

IP class **IP 40**

Recommend 0~40°C, under 85% RH environment

Certification CE, FCC, RoHS



^{*}② Using the optional communication protocol, an external communication conversion box is required. Please consult the sales staff for details.

DH-ROBOTICS





PGLS Series Industrial Flat Electric Grippers

PGLS-1200





Product Features

> Thin | High energy density

The PGLS-1200 heavy-duty electric gripper is compact in design and only 50mm thick. It has high gripping force, fast gripping cycle and built-in power-off hold function. This gripper challenges the limits of large load, compactness and thinness.

> High force control accuracy

The force repeatability is $\pm 120N(\pm 10\%)$, far better than ordinary products in the market by $\pm 10\% \sim \pm 20\%$ of force control accuracy.

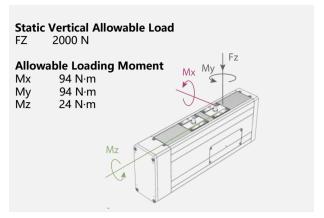
Quick response | Intelligent planning speed

Opening/closing time up to 2.0s/2.2s(100 stroke), with speed control optimization and mechanical self-locking mechanism function, it can meet fast and stable gripping needs of the production line.



■ PGLS-1200-100

> Product Parameter	
Gripping force(per jaw)	400~1200 N
Total stroke	100 mm
Recommend payload*①	12 kg
Opening/closing time	2.0 s/2.2 s
Repeat accuracy(position)	± 0.02 mm
Operating noise	< 75 dB
Weight	3.2 kg
Diving method	Precision reduction box + ball screw + built-in guide rail
Size	262 mm x 98 mm x 50 mm



*① It depends on factors such as the shape of the grasped object, the contact surface material and friction, and the acceleration of the movement; the center of gravity offset of the grasped object will also affect the load. If you have any questions, please consult us.

> Working Environment

Communication

Standard: IO-Link Modbus RTU (RS485), Optional: TCP/IP、USB2.0、CAN2.0A、PROFINET、EtherCAT *② interface

24 V DC ± 10% Rated voltage

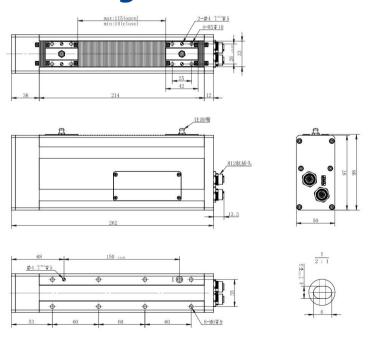
Rated current 4.5 A

Peak current 13.5 A

IP class **IP 40**

Recommend 0~40°C, under 85% RH environment

Certification CE, FCC, RoHS

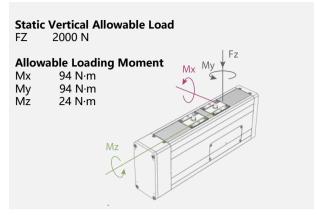


^{*}② Using the optional communication protocol, an external communication conversion box is required. Please consult the sales staff for details.



■ PGLS-1200-200

> Product Parameter	
Gripping force(per jaw)	400~1200 N
Total stroke	200 mm
Recommend payload*①	12 kg
Opening/closing time	4.0 s/4.2 s
Repeat accuracy(position)	± 0.02 mm
Operating noise	< 75 dB
Weight	4.2 kg
Diving method	Precision reduction box + ball screw + built-in guide rail
Size	382 mm x 98 mm x 50 mm



*① It depends on factors such as the shape of the grasped object, the contact surface material and friction, and the acceleration of the movement; the center of gravity offset of the grasped object will also affect the load. If you have any questions, please consult us.

> Working Environment

Communication interface

Standard: IO-Link Modbus RTU (RS485), Optional: TCP/IP、USB2.0、CAN2.0A、PROFINET、EtherCAT *②

Rated voltage 24 V DC ± 10%

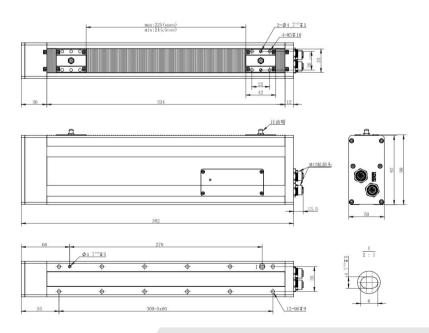
Rated current 4.5 A

Peak current 13.5 A

IP class **IP 40**

Recommend 0~40°C, under 85% RH environment

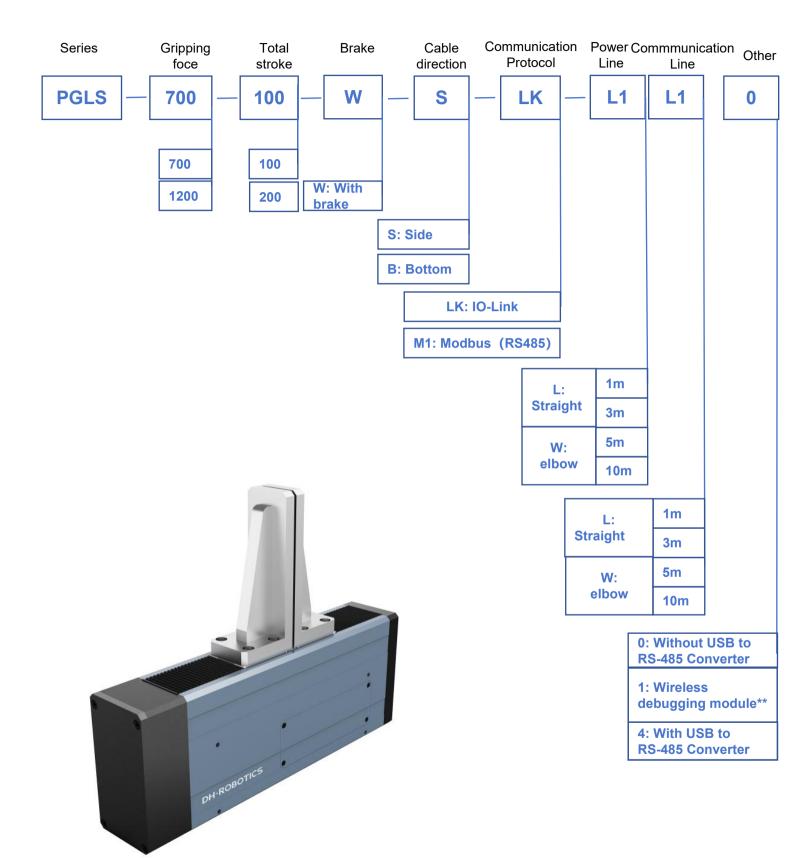
Certification CE, FCC, RoHS



^{*}② Using the optional communication protocol, an external communication conversion box is required. Please consult the sales staff for details.



Model Selection Method



*Note: IO-Link communication protocol recommends configuring a wireless debugging module